



Correlation coefficient

The measure of linear association between two variables X and Y

$$\gamma = \frac{S_{xy}}{\sqrt{S_{xx}S_{yy}}}, \quad -1 \leq \gamma \leq 1$$

where

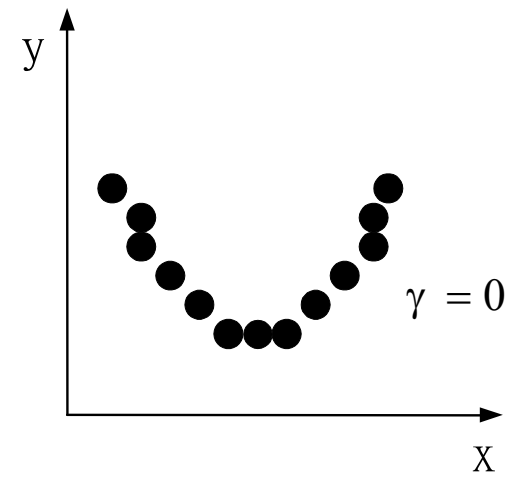
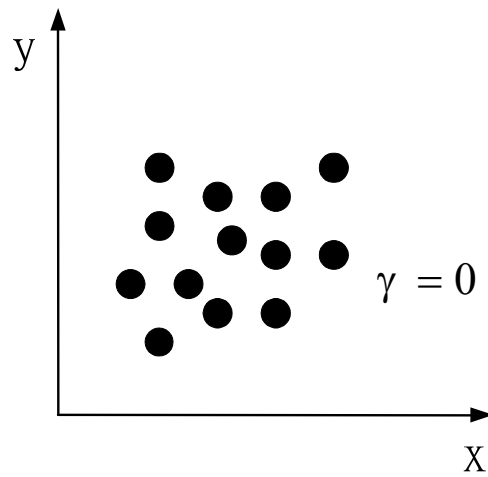
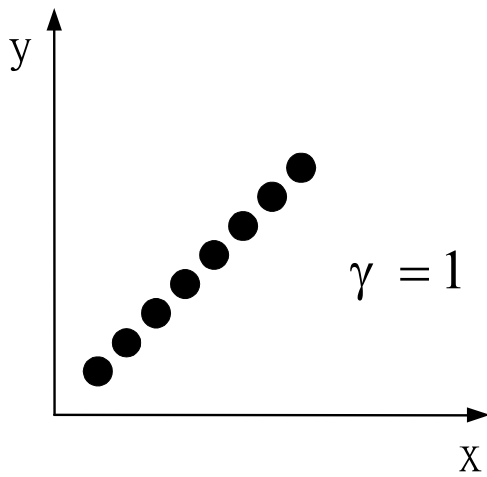
$$S_{xy} = \sum_{i=1}^n (x_i - \bar{x})(y_i - \bar{y})$$

$$S_{xx} = \sum_{i=1}^n (x_i - \bar{x})^2$$

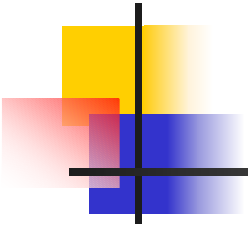
$$S_{yy} = \sum_{i=1}^n (y_i - \bar{y})^2$$

γ^2 : Sample coefficient of determination

- ⇒ Represent the proportion of the variation of S_{yy} explained by the regression of Y on X.
- ⇒ A γ of 0.9 means that 0.81(81%) of the total variation of Y in our sample can be explained by a linear relationship with values of X.



$\gamma = 0$ implies a lack of linearity, but not a lack of association.



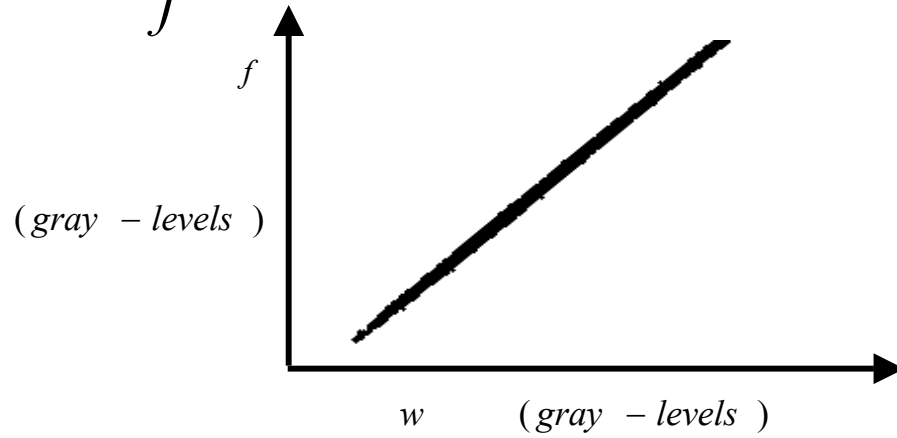
$$f = w$$

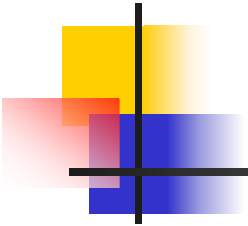


f



w





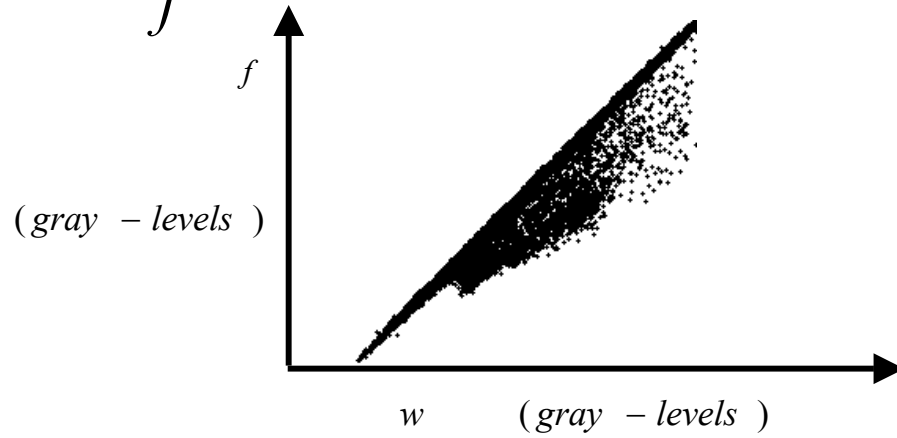
$$f \approx w$$

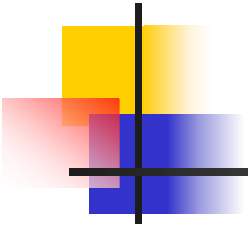


f

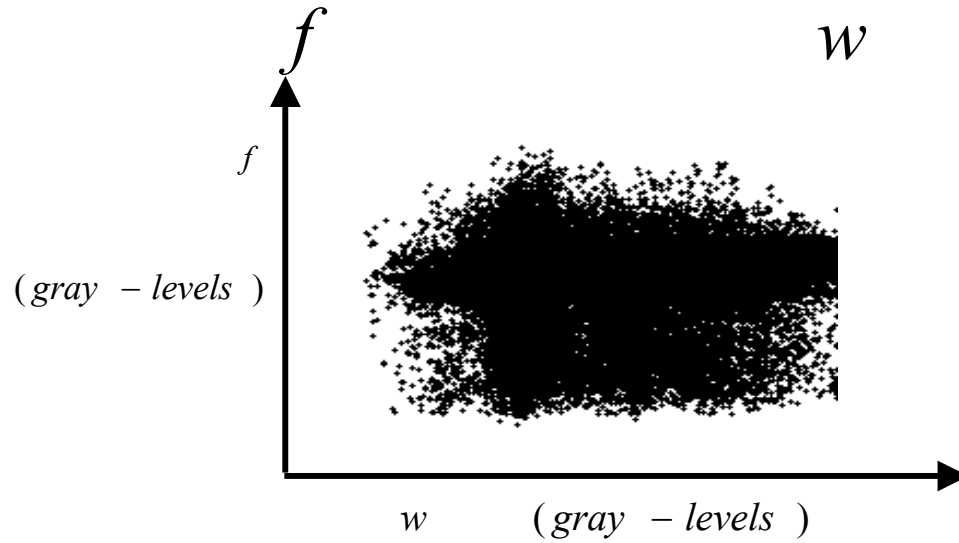
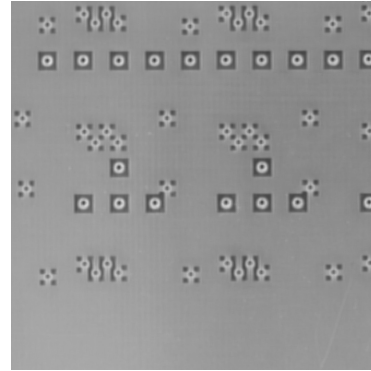


w





$$f \neq w$$





Matching by correlation

Correlation coefficients for 2D images

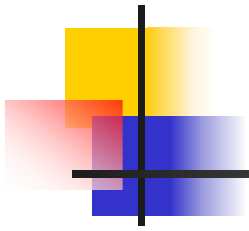
Given two images $f(x,y)$ and $w(l,m)$ $-k \leq l, m \leq k$ and $n=2k+1$

Let \bar{f} and \bar{w} be the mean gray levels of $f(x,y)$ and $w(l,m)$

$$\bar{f} = \frac{1}{n^2} \sum_{l=-k}^k \sum_{m=-k}^k f(x+l, y+m)$$

$$\bar{w} = \frac{1}{n^2} \sum_{l=-k}^k \sum_{m=-k}^k w(l,m)$$

$$\gamma(x,y) = \frac{\sum_l \sum_m [f(x+l, y+m) - \bar{f}] \cdot [w(l,m) - \bar{w}]}{\left\{ \sum_l \sum_m [f(x+l, y+m) - \bar{f}]^2 \cdot \sum_l \sum_m [w(l,m) - \bar{w}]^2 \right\}^{1/2}}$$



$$\gamma(x, y) = \frac{\sum_l \sum_m [f(x+l, y+m) \cdot w(l, m)] - n^2 \bar{f} \cdot \bar{w}}{\left[\left(\sum_l \sum_m f^2(x+l, y+m) - n^2 \bar{f}^2 \right) \left(\sum_l \sum_m w^2(l, m) - n^2 \bar{w}^2 \right) \right]^{1/2}}$$

Normalized measure: let $\bar{w}=0$

$$\gamma_N(x, y) = \frac{\sum_l \sum_m [f(x+l, y+m) \cdot w(l, m)]}{\left[\left(\sum_l \sum_m f^2(x+l, y+m) - n^2 \bar{f}^2 \right) \left(\sum_l \sum_m w^2(l, m) \right) \right]^{1/2}}$$

- Very sensitive to noise, poor detection
- Good localization



Cosine measure: Let $\bar{f} = 0$

Consider the two image f and w as two vectors \vec{F} and \vec{W} , then

$$\cos\theta = \frac{\vec{F} \cdot \vec{W}}{|\vec{F}| |\vec{W}|}$$

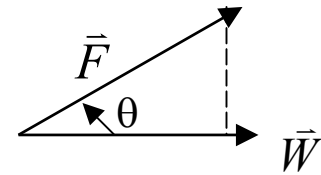
$$\gamma_{\theta}(x, y) = \frac{\sum_l \sum_m [f(x+l, y+m) \cdot w(l, m)]}{\left[\sum_l \sum_m f^2(x+l, y+m) \cdot \sum_l \sum_m w^2(l, m) \right]^{1/2}}$$

- Less sensitive to noise
- Mean localization



Projection measure: let $\sum \sum f^2(x+l, y+m) = 1$

$$\gamma_p(x, y) = \frac{\sum_l \sum_m [f(x+l, y+m) \cdot w(l, m)]}{\left[\sum_l \sum_m w^2(l, m) \right]^{1/2}}$$



- Least sensitive to noise, very good detection
- Poor localization

Convolution measure (cross correlation):

Let $\sum \sum w^2(l, m) = 1$

$$\gamma_c = \sum_l \sum_m f(x+l, y+m) \cdot w(l, m)$$



Subpixel matching

Interpolation around the peak of $\gamma(x, y)$ using
(second-degree polynomial) curve fitting

Let $\gamma(x, y) = \max\{\gamma(i, j) \mid (i, j) \in N(x, y)\}$

The subpixel correction term $(\Delta x, \Delta y)$:

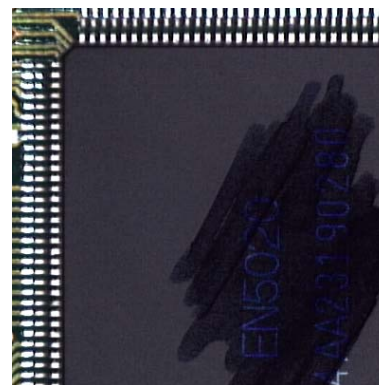
$$\Delta x = \frac{1}{2} \frac{\gamma(x-1, y) - \gamma(x+1, y)}{\gamma(x+1, y) + \gamma(x-1, y) - 2\gamma(x, y)}$$

$$\Delta y = \frac{1}{2} \frac{\gamma(x, y-1) - \gamma(x, y+1)}{\gamma(x, y+1) + \gamma(x, y-1) - 2\gamma(x, y)}$$

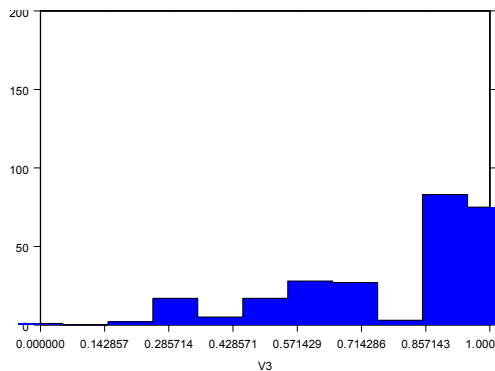
Effects of smoothing



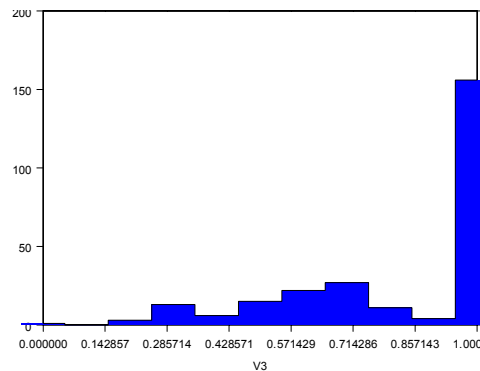
標準影像



待測影像



無smoothing



有smoothing

Correlation coefficient for color images

令 $\bar{C}_M(i, j)$ 為標準影像在像素點 (i, j) 的RGB向量， $\bar{C}_M(i, j) = (R(i, j), G(i, j), B(i, j))$
 $\bar{C}_S(x, y)$ 為測試影像在像素點 (x, y) 的RGB向量， $\bar{C}_S(x, y) = (\hat{R}(x, y), \hat{G}(x, y), \hat{B}(x, y))$
則定義標準圖形與待測圖形之彩色影像點相關係數 (γ_I) 為：

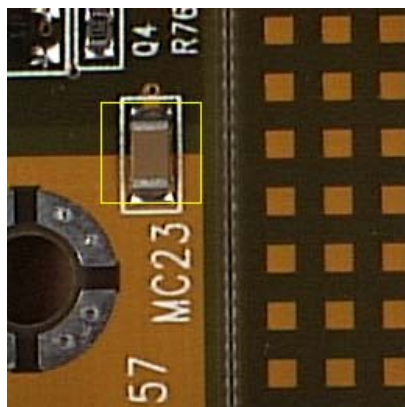
$$\gamma_I = \frac{\sum_i \sum_j \bar{C}_M(i, j) \cdot \bar{C}_S(x+i, y+j) - 3N_W \times \mu_I \times \hat{\mu}_I}{\sqrt{\left(\sum_i \sum_j T_I(i, j) - 3N_W \times \mu_I^2 \right) \times \left(\sum_i \sum_j \hat{T}_I(x+i, y+j) - 3N_W \times \hat{\mu}_I^2 \right)}}$$

其中 $T_I(i, j) = [R^2(i, j) + G^2(i, j) + B^2(i, j)]$

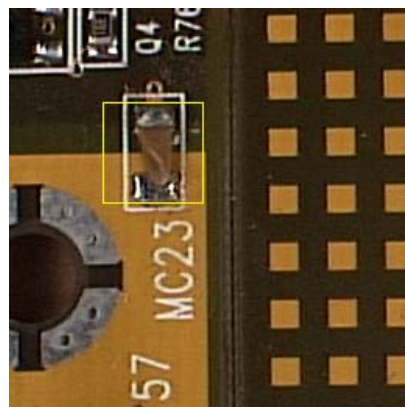
$$\hat{T}_I(x+i, y+j) = [\hat{R}^2(x+i, y+j) + \hat{G}^2(x+i, y+j) + \hat{B}^2(x+i, y+j)]$$

$$\mu_I = \frac{1}{3 \times N_W} \sum_{j=-v}^v \sum_{i=-W}^W [R(i, j) + G(i, j) + B(i, j)]$$

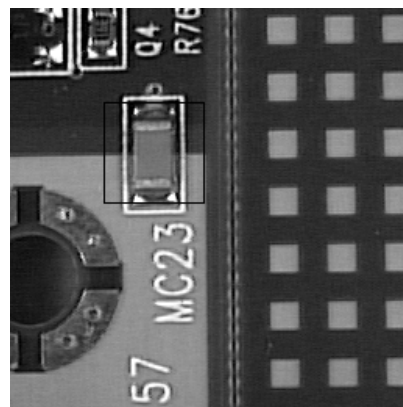
$$\hat{\mu}_I = \frac{1}{3 \times N_W} \sum_{j=-v}^v \sum_{i=-W}^W [\hat{R}(x+i, y+j) + \hat{G}(x+i, y+j) + \hat{B}(x+i, y+j)]$$



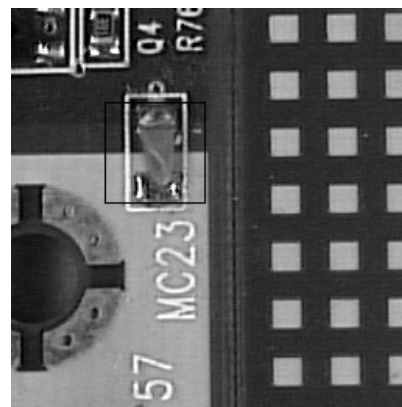
(a)



(b)



(c)



(d)

	彩色影像點比對法		灰階影像點比對法	
	正常影像	瑕疵影像	正常影像	瑕疵影像
	最大之相關係數值。			
影像圖	圖(a)	圖(b)。	圖(c)	圖(d)
平均值	0.936515	0.697862	0.916716	0.640878
標準差	0.001191	0.001679	0.001358	0.001877